

Center of Mass

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1 Definition

Average position of mass of an object; all mass of an object can be imagined to be concentrated at that point

2 Finding Center of Mass

Consider meter stick (platonic ideal). Where would center of mass be? Ideally, 50 cm.

Again, consider this amorphous blob:

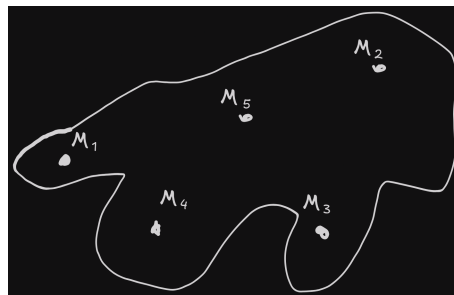


Figure 1: Object is divided into an infinitesimal amount of points. Center of mass is average of each x/y in each coordinate

2.1 Weighted average

$$\frac{m_1x_1 + m_2x_2 + m_3x_3 \dots + m_ix_i}{m_1 + m_2 + m_3 \dots m_i} \quad (1)$$

Better written as:

	Variable	Meaning
$\frac{1}{M} \sum_{i=1}^N m_ix_i \quad (2)$	M	total mass
	m_i	each mass point
	x_i	each x coordinate
	N	number of points (infinite)

3 Center of Mass In Motion

$$\vec{r}_{cm} = \frac{1}{M} \sum_{i=1}^N m_i \vec{r}_i \quad (3)$$

\vec{r} is position vector of center of mass and its components

What if components can move (ie. waterbottle with 2/3 water)? We shall improve:

$$\Delta \vec{r}_{cm} = \frac{1}{M} \sum_{i=1}^N m_i \Delta \vec{r}_i \quad (4)$$

$\Delta \vec{r}$ is change in position vector

Remember:

$$\vec{v} = \frac{\Delta \vec{r}}{\Delta t} \quad (5)$$

Extended to:

$$\vec{v}_{cm} = \frac{1}{M} \sum_{i=1}^N m_i \frac{\Delta \vec{r}}{\Delta t} \quad (6)$$

Finally:

$$\vec{v}_{cm} = \frac{1}{M} \sum_{i=1}^N m_i \vec{v}_i \quad (7)$$

Pretty cool aside: $m_i \vec{v}_i$ is momentum (mass \times velocity).

4 Translational Motion

4.1 Definition

rigid body moving from one point in space to another; ex: throwing a ball in a parabola

4.2 Considerations

Anything that is rotating is always accelerating (\vec{a}). Must reframe acceleration in our rotating system. Acceleration is 2nd order derivative of position

4.3 Angular Quantities

Variable	Meaning
θ	Angular position
$r \times d\theta$	Arc Length/ Angular Displacement
$\frac{d\theta}{dt} = \omega$	Angular velocity
$\frac{d^2\theta}{dt^2} = \frac{d\omega}{dt} = \alpha$	Angular acceleration
$\vec{L} = I \times \vec{\omega}$	Angular momentum
$I = \int r dm$	Moment of inertia (how hard to move at given angle)

4.4 Converting Angular Velocity to Linear Velocity

How can we relate angular/linear velocity of a body in circular motion?

$$\begin{aligned}r \times \theta &= s \\r &= \frac{d\theta}{dt} = \frac{ds}{dt} \\r \times \vec{\omega} &= \vec{v} \\r \times \frac{d\vec{\omega}}{dt} &= \frac{d\vec{v}}{dt} r \times \vec{\omega} = \vec{a}\end{aligned}$$

5 Examples

5.1 Basic

1. 3 2kg masses hung from meter stick. First is 7cm mark second at 12cm, third 25cm. Find center of mass.

$$\frac{2 \times 7 + 2 \times 12 + 2 \times 25}{6} = 14.67 \text{ cm mark} \quad (8)$$

2. From center of mass of sun to center of mass of Earth is 150×10^6 km away. The sun's mass is 1.989×10^{33} kg and Earth about 5.97×10^{24} kg. Find center of mass of the Earth-sun system.

$$\frac{0 \times (5.97 \times 10^{24}) + (150 \times 10^6)(1.989 \times 10^{33})}{2} = 1.49175 \times 10^{11} \quad (9)$$

5.2 Translational Motion

1. Record player moves at 0.55 revolutions per second. Convert to radians/seconds.

$$0.55 * 2\pi = 1.1\pi \frac{\text{m}}{\text{s}} \quad (10)$$

2. After stopping, takes 0.5 seconds to stop. Find angular acceleration.

$$\alpha = \frac{d\theta}{dt} = \frac{1.1\pi}{0.5} = 6.91 \frac{\text{m}}{\text{s}} \quad (11)$$

3. Find angular position after 8 seconds

$$1.1\pi \times 8 = 8.8\pi \text{ radians} \quad (12)$$

4. Tire spins $\frac{1}{5}$ revolutions in 0.05 seconds. Find ω .

$$\omega = \frac{0.4\pi}{0.05} = 8\pi \quad (13)$$

5. Find size of tire if linear velocity of edge of tire is 3 m/s (hint: $\vec{v} \rightarrow \vec{\omega}$)

$$s = r \times \theta \quad (14)$$

didn't get the answer for this one, we ran out of time

6 Homework

1. A turntable (radius of 20 cm) is spinning at 2π rad/sec. Find the linear velocities and accelerations of objects placed 5 cm, 11 cm, and 17 cm from the axis of rotation.

Find velocity using formula: $\vec{v} = r\omega$

$$\vec{v}_1 = 0.05 \times 2\pi = 0.1\pi \text{ m/s}$$

$$\vec{v}_2 = 0.11 \times 2\pi = 0.22\pi \text{ m/s}$$

$$\vec{v}_3 = 0.17 \times 2\pi = 0.34\pi \text{ m/s}$$

No acceleration because no change in velocity

2. Find the distances traveled by each object in 7 seconds.

Using formula: $d = \vec{v} \times t$

$$d_1 = 0.1\pi * 7 = 0.7\pi \text{ meters}$$

$$d_2 = 0.22\pi * 7 = 1.54\pi \text{ meters}$$

$$d_3 = 0.34\pi * 7 = 2.38\pi \text{ meters}$$

3. The object 5 cm from the axis is placed $\frac{1}{4} \pi$ radians from $\theta=0$, the 11 cm object is $2\frac{2}{3}\pi$ radians from $\theta=0$, and the 17 cm object is π radians from $\theta=0$. Each object has a mass of 1 kg. Find the center of mass

First, organize our information: $r_1 = 5$ cm and $\theta_1 = \frac{1}{4}\pi$ $r_2 = 11$ cm and $\theta_2 = \frac{2}{3}\pi$ $r_3 = 17$ cm and $\theta_3 = \pi$

Use formula:

$$\vec{r}_{\text{cm}} = \frac{1}{M} \sum_{i=1}^N m_i \vec{r}_i \quad (15)$$

Finding X coordinate:

$$x_1 = 5 * \cos \frac{1}{4}\pi = \frac{5\sqrt{2}}{2}$$

$$x_2 = 11 * \cos \frac{2}{3}\pi = 6.5$$

$$x_3 = 17 * \cos \pi = -17$$

CoM X coordinate:

$$\vec{r}_{\text{cm}} = \frac{1 \times \frac{5\sqrt{2}}{2} + 1 \times 6.5 + 1 \times -17}{3} = -6.32 \quad (16)$$

Finding Y coordinate:

$$y_1 = 5 * \sin(\frac{1}{4}\pi) = 5\frac{\sqrt{2}}{2}$$

$$y_2 = 11 * \sin(\frac{2}{3}\pi) = \frac{11\sqrt{3}}{2}$$

$$y_3 = 17 * \sin(\pi) = 0$$

CoM Y coordinate:

$$\vec{r}_{\text{cm}} = \frac{1 \times \frac{5\sqrt{2}}{2} + 1 \times \frac{11\sqrt{3}}{2} + 1 \times 0}{3} = 4.354 \quad (17)$$

Final Answer:

Center of mass is $(-6.32, 4.354)$